WHAT IS CLAIMED IS:

1	1.	A system for measuring a three-dimensional object, sa	id system
2	compr	orising:	

- a base: 3
- elongate measuring members operatively connected to said 4 base such that said elongate measuring members can be displaced with 5 respect to said base in response to a surface of said three-dimensional 6 object; and 7
- means for determining displaced distances of said elongate 8 9 measuring members due to said surface of said three-dimensional object, 10 said displaced distances of said elongate measuring members being measurements of said surface of said three-dimensional object. 11
- The system of claim 1 wherein said elongate measuring members 2. 1 are operatively connected to said base such that said elongate measuring 2 members can be displaced in a direction parallel to central axes of said 3 elongate measuring members, said central axes corresponding to the 4
- lengths of said elongate measuring members. 5
- The system of claim 1 wherein said determining means includes 1 3. mechanical sensors that are coupled to said base, said mechanical 2 sensors being configured to mechanically sense displacements of said 3 elongate measuring members. 4
- 4. The system of claim 1 wherein said determining means includes 1 optical sensors that are coupled to said base, said optical sensors being 2 configured to optically sense displacements of said elongate measuring 3 members.

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- 1 5. The system of claim 1 wherein said elongate measuring members
- 2 include displacement information embedded in said elongate measuring
- members, and wherein said determining means includes optical sensors
- 4 that are coupled to said base, said optical sensors being configured to
- 5 optically read said displacement information embedded in said elongate
- 6 measuring members.
- 1 6. The system of claim 5 wherein said elongate measuring members
- 2 have reflectivity that varies along the lengths of said elongate measuring
- members, said reflectivity of said elongate measuring members being said
- 4 displacement information embedded in said elongate measuring members.
- 7. The system of claim 5 wherein said elongate measuring members
- 2 have different codes along the lengths of said elongate measuring
- 3 members, said different codes of said elongate measuring members being
- 4 said displacement information embedded in said elongate measuring
- 5 members.
- 1 8. The system of claim 1 wherein said elongate measuring members
- 2 have transmissivity that varies along the lengths of said elongate
- 3 measuring members, and wherein said determining means includes light
- 4 sources and an imaging sensor, said light sources being positioned to
- 5 project lights into said elongate measuring members at locations along the
- 6 lengths of said elongate measuring members, said imaging sensor being
- 7 positioned to capture an image of light-emitting ends of said elongate
- 8 measuring members.

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- 9. The system of claim 8 further comprising a processing unit
- 2 configured to process said image to determine intensities of lights emitted
- from said light-emitting ends of said elongate measuring members, said
- 4 intensities of lights corresponding to said displaced distances of said
- 5 elongate measuring members.

- 1 10. A system for measuring a three-dimensional object, said system 2 comprising:
- a base;
- 4 elongate measuring members operatively connected to said
- base such that said elongate measuring members can be displaced with
- 6 respect to said base in response to a surface of said three-dimensional
- object; and
- 8 a displacement-determining mechanism operatively coupled
- 9 to said elongate measuring members, said displacement-determining
- mechanism being configured to determine displaced distances of said
- elongate measuring members due to said surface of said three-
- dimensional object, said displaced distances of said elongate measuring
- 13 members being measurements of said surface of said three-dimensional
- 14 object.
- 1 11. The system of claim 10 wherein said elongate measuring members
- 2 are operatively connected to said base such that said elongate measuring
- members can be displaced in a direction parallel to central axes of said
- 4 elongate measuring members, said central axes corresponding to the
- 5 lengths of said elongate measuring members.
- 1 12. The system of claim 10 wherein said displacement-determining
- 2 mechanism includes mechanical sensors that are coupled to said base,
- 3 said mechanical sensors being configured to mechanically sense
- 4 displacements of said elongate measuring members.
- 1 13. The system of claim 10 wherein said displacement-determining
- 2 mechanism includes optical sensors that are coupled to said base, said
- 3 optical sensors being configured to optically sense displacements of said
- 4 elongate measuring members.

- 1 14. The system of claim 10 wherein said elongate measuring members
- 2 include displacement information embedded in said elongate measuring
- 3 members, and wherein said displacement-determining mechanism
- 4 includes optical sensors that are coupled to said base, said optical sensors
- 5 being configured to optically read said displacement information
- 6 embedded in said elongate measuring members.
- 1 15. The system of claim 14 wherein said elongate measuring members
- 2 have reflectivity that varies along the lengths of said elongate measuring
- members, said reflectivity of said elongate measuring members being said
- 4 displacement information embedded in said elongate measuring members.
- 1 16. The system of claim 14 wherein said elongate measuring members
- 2 have different codes along the lengths of said elongate measuring
- members, said different codes of said elongate measuring members being
- 4 said displacement information embedded in said elongate measuring
- 5 members.
- 1 17. The system of claim 10 wherein said elongate measuring members
- 2 have transmissivity that varies along the lengths of said elongate
- 3 measuring members, and wherein said displacement-determining
- 4 mechanism includes light sources and an imaging sensor, said light
- sources being positioned to project lights into said elongate measuring
- 6 members at locations along the lengths of said elongate measuring
- 7 members, said imaging sensor being positioned to capture an image of
- 8 light-emitting ends of said elongate measuring members.
- 1 18. The system of claim 17 further comprising a processing unit
- 2 configured to process said image to determine intensities of lights emitted
- 3 from said light-emitting ends of said elongate measuring members, said
- 4 intensities of lights corresponding to said displaced distances of said
- 5 elongate measuring members.

- 1 19. A method for measuring a three-dimensional object, said method comprising:
- engaging a surface of said three-dimensional object with
- 4 displaceable measuring members, including displacing said displaceable
- 5 measuring members in response to said surface of said three-dimensional
- 6 object; and
- 7 determining displaced distances of said displaceable
- 8 measuring members, said displaced distances providing measurements of
- 9 said surface of said three-dimensional object.
- 1 20. The method of claim 19 wherein said displacing of said
- 2 displaceable measuring members includes displacing said displaceable
- 3 measuring members in a direction parallel to central axes of said
- 4 displaceable measuring members, said central axes corresponding to the
- 5 lengths of said displaceable measuring members.
- 1 21. The method of claim 19 wherein said determining of said displaced
- 2 distances includes mechanically sensing displacements of said
- 3 displaceable measuring members.
- 1 22. The method of claim 19 wherein said determining of said displaced
- 2 distances includes optically sensing displacements of said displaceable
- 3 measuring members.
- 1 23. The method of claim 19 wherein said determining of said displaced
- 2 distances includes reading displacement information embedded in said
- 3 displaceable measuring members.
- 1 24. The method of claim 23 wherein said reading of said displacement
- 2 information includes measuring light reflected off locations along the
- 3 lengths of said displaceable measuring members, said displaceable
- 4 measuring members having reflectivity that varies along the lengths of said
- 5 displaceable measuring members.

- 1 25. The method of claim 23 wherein said reading of said displacement
- 2 information includes reading codes on said displaceable measuring
- 3 members, said displaceable measuring members having different codes
- 4 along the lengths of said displaceable measuring members.
- 1 26. The method of claim 19 wherein said determining of said displaced
- 2 distances includes projecting lights into said displaceable measuring
- 3 members at locations along the lengths of said displaceable measuring
- 4 members and capturing an image of light-emitting ends of said
- 5 displaceable measuring members, said displaceable measuring members
- 6 having transmissivity that varies along the lengths of said displaceable
- 7 measuring members.
- 1 27. The method of claim 26 further comprising processing said image to
- determine intensities of lights emitted from said light-emitting ends of said
- 3 displaceable measuring members, said intensities of lights corresponding
- 4 to said displaced distances of said elongate measuring members.